



## Microelectronic force sensors H Series

- Operating force range from 0-100 to 0-300 N
- Operating temperature range from -50 to +80 °C
- Electrical insulation strength – 500 V
- Titanium body



### Applications

- Industrial automation

- The sensors are intended for proportional conversion of force into electric signal.

### New solutions in pressure measurement – “Silicon-on-Sapphire” Technology

- ✓ Sensitive element of pressure sensors is a two-layer sapphire-titanium diaphragm with monocrystal silicon resistance strain gauges.
- ✓ Monocrystal sapphire diaphragm is a perfect elastic element that due to connection with titanium acquires the best quality as to the deformation level, and preserves its elastic properties up to +400°C.
- ✓ Monocrystal silicon resistance strain gauges are automatically connected with sapphire (heteroepitaxy method) and provide almost no hysteresis or fatigue effects.
- ✓ Exceptional insulating properties and radiation resistance of sapphire enable to use the sensitive element within temperature range from -200 to +350°C under the effect of high electromagnetic interferences and radiation.
- ✓ Strain gauges elements are manufactured in groups by solid-state micro-electronic methods and provide high quality and good repeatability of the output parameters.

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# Datasheet

## 1 Nominal and overload force

Designation	Nominal force, N	Overload force, N
H 100-1	from 0 to 100	from 0 to 200
H 200-1	from 0 to 200	from 0 to 400
H 300-1	from 0 to 300	from 0 to 600
H 100-2	from 0 to 100	from 0 to 200
H 200-2	from 0 to 200	from 0 to 400
H 300-2	from 0 to 300	from 0 to 600

## 2 Temperature ranges

- 2.1 Operating temperature range ..... from - 50 to + 80°C  
2.2 Limiting temperature range ..... from - 60 to + 130°C

## 3 Accuracy parameters

- 3.1 Non-linearity, % FS ..... ±0,2  
3.2 Variation, % FS ..... 0,1  
3.3 Long-term stability of the output signal range within 12 months, % ..... ±0,2  
3.4 Output signal error caused by the influence of overload pressures, % FS  
    for zero output signal ..... ±0,15  
    for output signal range ..... ±0,1  
3.5 Additional ambient temperature error, % FS/1°C  
    3.5.1 For zero output signal ..... ±0,05  
    3.5.2 For output signal range ..... -0,02±0,05

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3.6 Additional vibration error of the output signal, % FS ..... ±0,1

#### 4 Electrical characteristics

4.1 Output signal at room temperature, mV

    4.1.1 Zero output signal ..... ±15

    4.1.2 Output signal range (FS) ..... 200±50

4.2 Strain gauge bridge resistance at room temperature, kOhm ..... 3,25±0,25

4.3 Insulation resistance, MOhm

    at room temperature ..... 100

    at the upper ambient temperature value ..... 5

4.4 Electrical insulation strength (AC voltage), V

    for version 1 ..... 150

    for version 2 ..... 500

4.5 Power supply - stabilized DC, mA ..... 2±0,3

    Output signal is rated by the current, mA ..... 2±0,004

#### 5 Mechanical characteristics

5.1 Vibration resistance (sinusoidal vibration):

    Frequency range, Hz ..... from 10 to 2000

    Acceleration amplitude, m/s<sup>2</sup> ..... 100

5.2 Shock resistance (multiple mechanical shocks):

    Shock acceleration peak, m/s<sup>2</sup> ..... 1000

    Shock pulse width, ms ..... 1-3

#### 6 Operating conditions

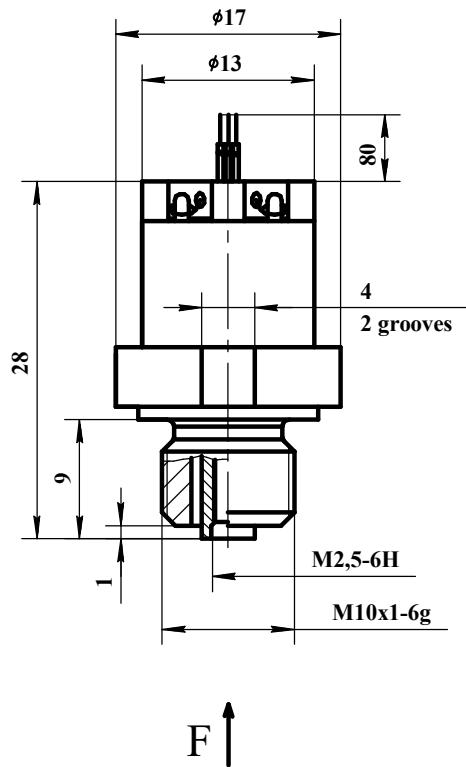
6.1 IP level ..... IP30

6.2 Sensor body and membrane are made

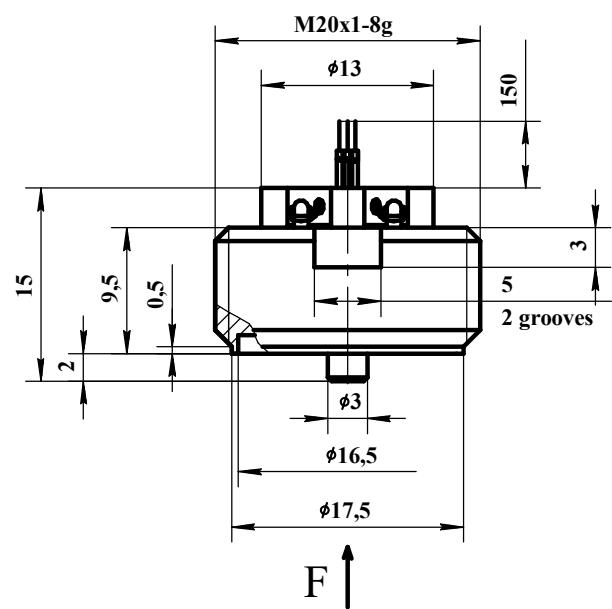
    of titanium alloy with 87 % of titanium.

## 7 Overall and mounting dimensions

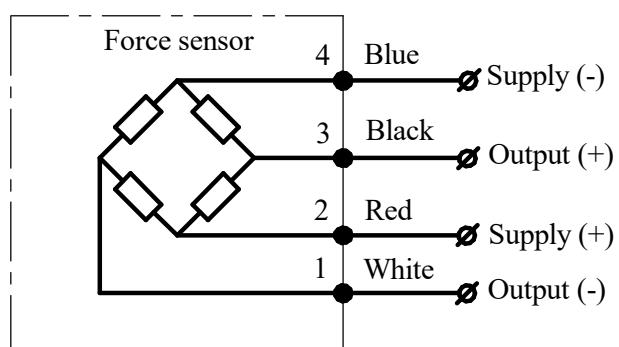
### 7.1 Force sensors of version 1



### 7.2 Force sensors of version 2



## 8 Circuit diagram



## 9 Type designation

H XXX - X

Series

Upper force limit

100, 200, 300 N

Version of force sensors

1 - fitting thread M10x1;  
2 - fitting thread M20x1

Order example of force sensor

Force sensor of H series, intended for force conversion from 0 to 100 N,  
with fitting thread M10x1:

Force sensor H 100-1.

Note: if wished, the wire length (standard 80 mm) can be changed, in this case  
the required length should be added to the wire code L, for example:

Force sensor H 100-1-L130.

## 10 Marking

Marking on the sensor body must contain following information:  
designation of the sensor and order number.

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